

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY HYDERABAD

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Lecture-11 By Vivek Dubey

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COMPUTER SCIENCE AND ENGINEERING

CS403PC

COMPUTER SCIENCE AND ENGINEERING (ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING)

CS403PC

BHARAT INSTITUTE OF ENGINEERING AND TECHNOLOGY

Scheme of Operating System

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S. No.	Course Code	Course Title	L	T	P	Credits
3	CS403PC	Operating Systems	3	0	0	3
6	CS406PC	Operating Systems Lab	0	0	3	1.5

UNIT-2:

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- **Process and CPU Scheduling –**
 - Process concepts and scheduling, Operations on Processes, Cooperating Processes, Threads, and **Inter Process Communication (IPC)**, Scheduling Criteria, Scheduling Algorithms, Multiple - Processor Scheduling.
- **System call interface for process management-**
 - fork, exit, wait, waitpid, exec



Cooperating Processes and IPC

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- A process can either be independent or co-operate with other processes.
- Any process that shares data with other processes can be called as a cooperating process.
- Cooperating processes require an inter-process communication (IPC) mechanism for exchanging data and information between processes.

Cooperating Processes and IPC

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- Cooperating processes are those that **can affect** or **are affected** by other processes running on the system.
- Cooperating processes **may share** data with each other.
- There may be many reasons for the requirement of cooperating processes.
- Some of these are given as follows –
 - ✓ Modularity
 - ✓ Information Sharing
 - ✓ Convenience
 - ✓ Computation Speedup

• Modularity

- Modularity involves *dividing complicated tasks* into smaller subtasks.
- These subtasks *can be completed* by different cooperating processes.
- This *leads* to faster and more efficient completion *of the required tasks*.

• Information Sharing

- Sharing of information between multiple processes *can be accomplished* using cooperating processes.
- This *may include access* to the same files.
- A mechanism *is required* so that the processes *can access* the files in parallel to each other.

• Convenience

- There are many tasks that a user needs to do *such as compiling, printing, editing etc.*
- It is convenient if these tasks can be managed *by cooperating processes*.

• Computation Speedup

- Subtasks of a single task *can be performed parallelly* *using cooperating processes*.
- This increases the computation speedup *as the task can be executed faster*.
- However, this is only possible *if the system has multiple processing elements*.

Methods of Cooperation

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- *There are two fundamental models* of interprocess communication:

- ✓ Cooperation by Sharing

- ✓ Cooperating Processes

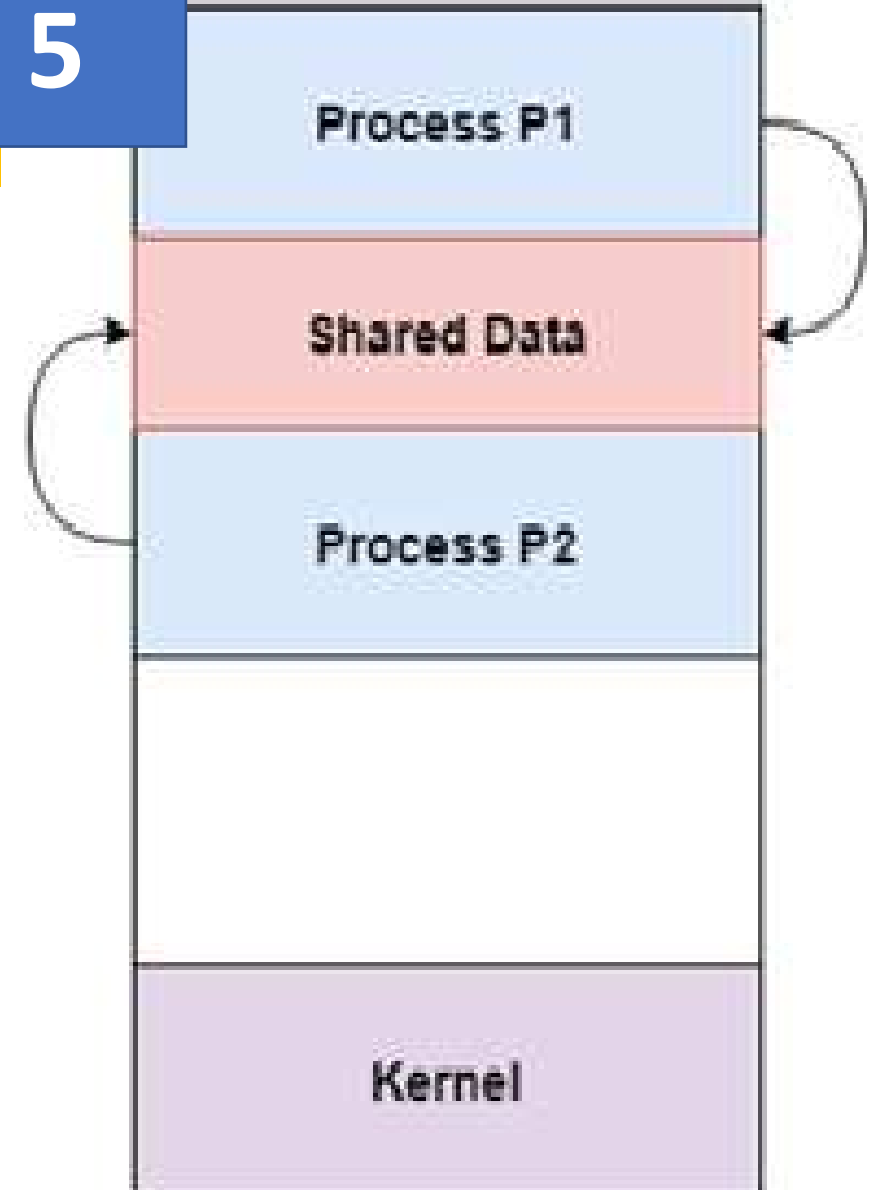
Cooperation by Sharing

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- The cooperating processes **can cooperate with each other using shared data** such as memory, variables, files, databases etc.
- Critical section **is used to provide data integrity** and **writing is mutually exclusive** to prevent inconsistent data.
- In the diagram, **Process P1 and P2 can cooperate with each other using shared data** such as memory, variables, files, databases etc.



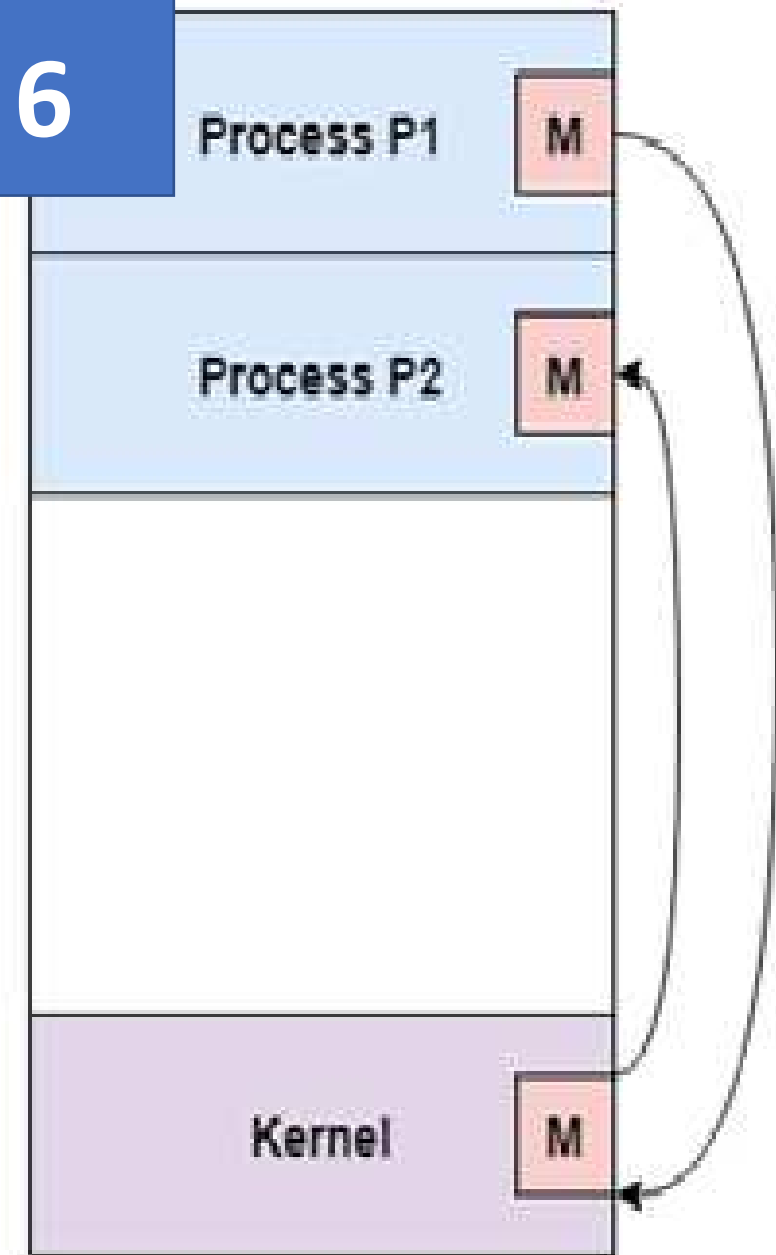
Cooperating Processes

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- The cooperating processes ***can cooperate with each other using messages.***
- **This may lead to deadlock** *if each process is waiting for a message from the other to perform an operation.*
- **Starvation is also possible** *if a process never receives a message.*
- A diagram that demonstrates cooperation by communication –



Communication Link

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- A communication link must exist between sender and receiver.
- For logical link implementation, the following methods:
 - **Direct or indirect** communication
 - **Synchronous or asynchronous** communication
 - **Automatic or explicit** buffering

Direct Communication

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- Direct communication: Each process that wants to communicate **must explicitly** name the recipient or sender of the communication.
- For example,
 - `send(P, message)`—*Send a message to process P.*
 - `receive(Q, message)`—*Receive a message from process Q.*
- Its properties are,
 - A link is established automatically between every pair of process.
 - The processes need to know only other's identity
 - A link is associated with exactly two processes.
 - Between each pair of processes, there exists exactly one link.

Indirect Communication

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- **Indirect communication:** The messages are sent to and received from mailboxes, or ports.
 - Each mailbox has a unique identification.
 - Two processes can communicate only if they have a shared mailbox.
 - A mailbox may be owned either by a process or by the operating system.
- The send() and receive() operations **are defined as follows:**
 - **send(A, message)**—Send a message to mailbox A.
 - **receive(A, message)**—Receive a message from mailbox A.
- Its properties are,
 - A link is established only if both members of the pair have a shared mailbox.
 - A link may be associated with more than two processes.
 - Between each pair of communicating processes, a number of different links may exist, with each link corresponding to one mailbox.

Synchronous or Asynchronous Communication

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- Message passing may be either **synchronous** and **asynchronous** also known as blocking or nonblocking.
 - **Blocking send.** The sending process is blocked until the message is received.
 - **Nonblocking send.** The sending process sends the message and resumes operation.
 - **Blocking receive.** The receiver blocks until a message is available.
 - **Nonblocking receive.** The receiver retrieves either a valid message or a null.



Automatic or Explicit Buffering

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- Messages exchanged *by communicating processes* reside in a temporary queue.
- Basically, such queue can be implemented in three ways:
 - Message system with no buffering:
 1. Zero Capacity.
 - Message system with automatic buffering:
 2. Bounded Capacity and
 3. Unbounded Capacity

Message System with No Buffering

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- **Message system with no buffering:**

- ✓ *Zero capacity.*

- No messages are queued on a link.

- *Sender must wait for receiver.*

Message System with Automatic Buffering



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✓ Bounded capacity:

- The queue has *finite length n* .
- Sender must wait, *if link is full*.



Message System with Automatic Buffering

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- ✓ **Unbounded capacity:**
 - The queue's length is ***infinite***;
 - Sender ***never wait***.

CLASSICAL PROBLEM OF SYNCHRONIZATION



- Following are *some of the classical problem* faced while process synchronization *in systems* where cooperating processes are present:

- ✓ Bounded Buffer Problem
- ✓ The Readers Writers Problem
- ✓ Dining Philosophers Problem

Bounded Buffer Problem

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- The bounded-buffer problems (the producer-consumer problem) is a classic example of concurrent access to a shared resource.
- A bounded buffer **lets** multiple producers and multiple consumers share a single buffer.
- **Producers write data to the buffer and consumers read data from the buffer:**
 - Producers must block if the buffer is full.
 - Consumers must block if the buffer is empty.

The Readers Writers Problem

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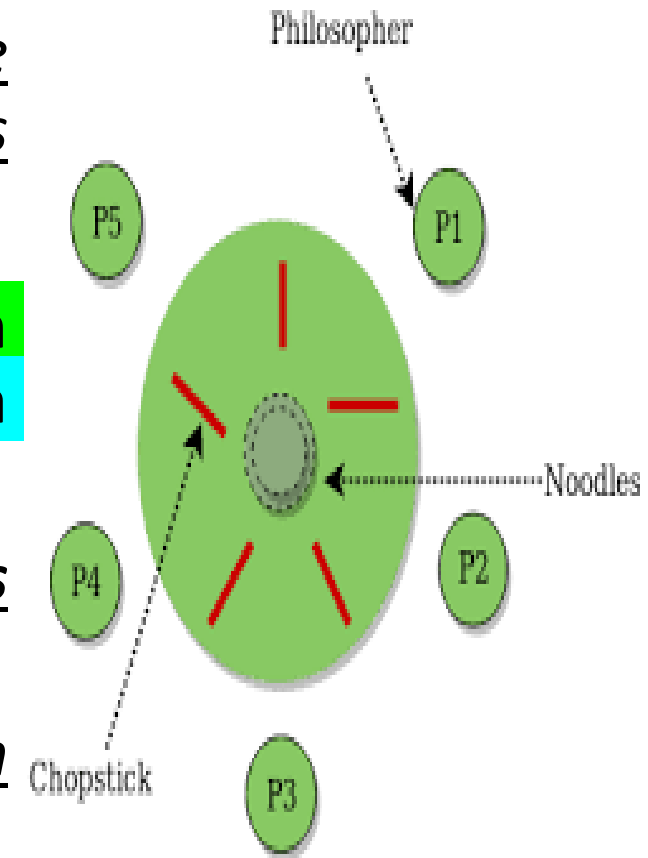


- A resource is shared among many processes, each belonging to one of two processes. They are either **reader** or **writer**.
- *In this problem*, any number of readers can read from the shared resource simultaneously, **but at a time only** one writer can write to the shared resource.
- Also, when a writer *is writing data to the resource*, at that time no other process can access the resource.
- Readers do not write, readers only read.
- If a process is writing, no other process can read it.

Dining Philosophers Problem

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- The dining philosopher's problem involves the allocation of limited resources from a group of processes in a deadlock-free and starvation-free manner.
- There are five philosophers sitting around a table, in which there are five chopsticks kept beside them and a bowl of rice in the center.
- When a philosopher wants to eat, he uses two chopsticks - one from their left and one from their right.
- When a philosopher wants to think, he keeps down both chopsticks at their original place.



Deadlock Problem

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- A Process or thread enters a waiting state because a requested system resource is held by another waiting process.

Starvation Problem

- When high priority processes keep executing and low priority processes get blocked for indefinite time.